

Calculation of Generalized Pauli Constraints

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Notations

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ρ is a non-negative ($\rho \geq 0$) Hermitian operator with $\text{Tr}\rho = 1$, called **Density matrix**.

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Density Matrix of Composite Systems

Density matrix of composite system can be written as linear combination

$$\rho_{AB} = \sum_{\alpha} a_{\alpha} L_A^{\alpha} \otimes L_B^{\alpha}$$

where L_A^{α} , L_B^{α} are linear operators on \mathcal{H}_A , \mathcal{H}_B , respectively.

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they are called one-particle reduced density matrices.

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- This implies the original Pauli principle, because $\psi \wedge \psi = 0$.

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Mixed N -representability

More generally we have mixed N -representability problem:
“What are the constraints on the spectra of a mixed state and its reduced matrix?”

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Two-particle ($\wedge^2 \mathcal{H}_r$) and Two-hole ($\wedge^{r-2} \mathcal{H}_r$) systems

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- Similar results hold for two-hole system.

What was known before 2008?

Borland-Dennis system

- For the system $\wedge^3\mathcal{H}_6$ of three electrons of rank 6, the N -representability conditions are given by the following (in)equalities:

$$\lambda_1 + \lambda_6 = \lambda_2 + \lambda_5 = \lambda_3 + \lambda_4 = 1, \quad \lambda_4 \leq \lambda_5 + \lambda_6,$$

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- Sufficiency proved by Borland-Dennis (1972)
- Necessity proved by Ruskai (2007)

Formal Solution of Mixed N -representability

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Main Theorem. Let $\rho^N : \wedge^N \mathcal{H}_r$ ($\text{Tr} \rho^N = 1$) be mixed state and $\rho : \mathcal{H}_r$ ($\text{Tr} \rho = N$) be its particle density matrix.

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$$\sum_i a_i \lambda_{v(i)} \leq \sum_k (\wedge^N a)_k \mu_{w(k)} \quad (a, v, w)$$

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$$\sum_i a_i \lambda_{v(i)} \leq \sum_k (\wedge^N a)_k \mu_{w(k)} \quad (a, v, w)$$

Here, $\wedge^N a$ consists of all sums $a_{i_1} + a_{i_2} + \dots + a_{i_N}$, $1 \leq i_1 < i_2 < \dots < i_N \leq r$ arranged in decreasing order, $v \in S_r$ and $w \in S_R$ subject to topological condition $c_v^w(a) \neq 0$ explained soon.

Solution of Pure N -representability

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In this case all constraints together with ordering inequalities and normalization condition describe a convex polytope, called Moment Polytope.

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and morphism

$$\begin{aligned} \varphi_a : \mathcal{F}_a(\mathcal{H}_r) &\rightarrow \mathcal{F}_{\wedge^N a}(\wedge^N \mathcal{H}_r) \\ X &\mapsto X^{(N)} \end{aligned}$$

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Here, $X^{(N)} : \psi_1 \wedge \psi_2 \wedge \dots \wedge \psi_N \mapsto \sum_i \psi_1 \wedge \psi_2 \wedge \dots \wedge X\psi_i \wedge \dots \wedge \psi_N$.

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written in the basis of Schubert cocycles σ_w .

Connection with Representation Theory


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
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
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“Which irreducible representations \mathcal{H}_λ of $U(\mathcal{H}_r)$ can appear in the decomposition of $S^m(\wedge^N \mathcal{H}_r)$?”

Surprisingly solution of this problem coincides with that of pure N -representability problem.

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Representation theoretical solution

Theorem. Every $\tilde{\lambda}$ obtained from irreducible component $\mathcal{H}_\lambda \subset S^m(\wedge^N \mathcal{H}_r)$ is a spectrum of one point reduced matrix ρ of a pure state $\psi \in \wedge^N \mathcal{H}_r$.

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Practical Algorithm

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- Find all irreducible components $\mathcal{H}_\lambda \subset S^m(\wedge^N \mathcal{H}_r)$ for $m \leq M$.

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- Increase M and continue until $\mathcal{P}_M^{\text{in}} = \mathcal{P}_M^{\text{out}}$.

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m	λ
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2	[2, 2, 2, 0, 0, 0], [2, 1, 1, 1, 1, 0]
3	[2, 2, 2, 1, 1, 1], [3, 3, 3, 0, 0, 0], [3, 2, 2, 1, 1, 0]
4	[2, 2, 2, 2, 2, 2], [3, 3, 3, 1, 1, 1], [4, 4, 4, 0, 0, 0], [3, 3, 2, 2, 1, 1], [4, 3, 3, 1, 1, 0], [4, 2, 2, 2, 2, 0]

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3	$[\frac{2}{3}, \frac{2}{3}, \frac{2}{3}, \frac{2}{3}, \frac{1}{3}, \frac{1}{3}], [1, 1, 1, 0, 0, 0], [1, \frac{2}{3}, \frac{2}{3}, \frac{1}{3}, \frac{1}{3}, 0]$
4	$[\frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}], [\frac{3}{4}, \frac{3}{4}, \frac{3}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4}], [1, 1, 1, 0, 0, 0],$ $[\frac{3}{4}, \frac{3}{4}, \frac{1}{2}, \frac{1}{2}, \frac{1}{4}, \frac{1}{4}], [1, \frac{3}{4}, \frac{3}{4}, \frac{1}{4}, \frac{1}{4}, 0], [1, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, 0]$

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3	$[\frac{2}{3}, \frac{2}{3}, \frac{2}{3}, \frac{2}{3}, \frac{1}{3}, \frac{1}{3}], [1, 1, 1, 0, 0, 0], [1, \frac{2}{3}, \frac{2}{3}, \frac{1}{3}, \frac{1}{3}, 0]$
4	$[\frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}], [\frac{3}{4}, \frac{3}{4}, \frac{3}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4}], [1, 1, 1, 0, 0, 0],$ $[\frac{3}{4}, \frac{3}{4}, \frac{1}{2}, \frac{1}{2}, \frac{1}{4}, \frac{1}{4}], [1, \frac{3}{4}, \frac{3}{4}, \frac{1}{4}, \frac{1}{4}, 0], [1, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, 0]$

Taking convex hull of these spectra we obtain the full moment polytope which is described by 3 equalities and 1 inequality.

How it works?

Borland-Dennis System ($N = 3, r = 6$)

After the normalization we obtain the spectra $\tilde{\lambda}$

m	$\tilde{\lambda}$
1	$[1, 1, 1, 0, 0, 0]$
2	$[1, 1, 1, 0, 0, 0], [1, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, 0]$
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4	$[\frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}], [\frac{3}{4}, \frac{3}{4}, \frac{3}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4}], [1, 1, 1, 0, 0, 0],$ $[\frac{3}{4}, \frac{3}{4}, \frac{1}{2}, \frac{1}{2}, \frac{1}{4}, \frac{1}{4}], [1, \frac{3}{4}, \frac{3}{4}, \frac{1}{4}, \frac{1}{4}, 0], [1, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, 0]$

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$M = 8.$

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$N = 3, r = 7$

$M = 8.$

$N = 4, r = 8$

$M = 10.$

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Thus the polytope is the genuine moment polytope for $\wedge^3 \mathcal{H}_8$ which is given by 31 independent inequalities.

Number of Constraints for systems of rank ≤ 10

r	N	Number of constraints
7	3	4
8	3	31
8	4	15
9	3	52
9	4	60
10	3	93
10	4	125
10	5	161

Thank You for your attention!!!